# Fine-Grained Complexity of Regular Path Queries 

Katrin Casel ${ }^{1}$, Markus L. Schmid ${ }^{2}$

${ }^{1} \mathrm{HPI}$, University of Potsdam, Germany
${ }^{2}$ HU Berlin, Germany

Graph Databases and Regular Path Queries

## Querying Graphs with Regular Expressions

## Graph databases

directed, edge-labelled multigraphs.

## Querying Graphs with Regular Expressions

## Graph databases

 directed, edge-labelled multigraphs.
## Graph Databases

$\Sigma_{\mathcal{D}}$
$V^{\prime}$
finite alphabet (edge labels)
vertices (or nodes)
$E_{\mathcal{D}} \subseteq V_{\mathcal{D}} \times \Sigma \times V_{\mathcal{D}} \quad$ edges (or arcs)
Graph database
$\mathcal{D}=\left(V_{\mathcal{D}}, E_{\mathcal{D}}\right)$

## Querying Graphs with Regular Expressions

## Graph databases

 directed, edge-labelled multigraphs.
## Graph Databases

```
\(\Sigma \quad\) finite alphabet (edge labels)
\(V_{\mathcal{D}} \quad\) vertices (or nodes)
\(E_{\mathcal{D}} \subseteq V_{\mathcal{D}} \times \Sigma \times V_{\mathcal{D}} \quad\) edges (or arcs)
Graph database
\(\mathcal{D}=\left(V_{\mathcal{D}}, E_{\mathcal{D}}\right)\)
```


## Regular Path Queries (RPQs)

Regular expressions $q$ over $\Sigma$.
$q(\mathcal{D})=\{(u, v) \mid \exists u$-to- $v$ path labelled by a word from $\mathcal{L}(q)\}$

## Regular Path Query Example

Graph database $\mathcal{D}$ :


## Regular Path Query Example

Graph database $\mathcal{D}$ :


Regular path query:

$$
q=a^{*}(b \vee c)
$$

## Different Variants of RPQs

## Different Variants of RPQs

Query results:

- Only node pairs $(u, v)$.
- Node pairs $(u, v)$ and a witness path.
- Node pairs $(u, v)$ and all witness paths.


## Different Variants of RPQs

Query results:

- Only node pairs $(u, v)$.
- Node pairs $(u, v)$ and a witness path.
- Node pairs $(u, v)$ and all witness paths.

Path semantics: $(u, v) \in q(\mathcal{D})$ if there is

- an arbitrary path.
- a simple path.
- a trail.
- a shortest path.


## Product Graph Approach (PG-Approach)

D: Graph database
$q$ : Regular path query
M: NFA for $q$ with state set $Q$

## Product Graph Approach (PG-Approach)

D: Graph database
$q$ : Regular path query
M: NFA for $q$ with state set $Q$

## Product Graph

$$
\begin{aligned}
& G(\mathcal{D}, q)=(V(\mathcal{D}, q), E(\mathcal{D}, q)) \\
& V(\mathcal{D}, q)=V_{\mathcal{D}} \times Q \\
& E(\mathcal{D}, q) \subseteq(V(\mathcal{D}, q) \times V(\mathcal{D}, q)):
\end{aligned}
$$

$$
(u, p) \rightarrow\left(v, p^{\prime}\right) \Longleftrightarrow \exists x \in \Sigma: u \xrightarrow{x} v \wedge p \xrightarrow{x} p^{\prime} .
$$

## PG-Approach Example



## PG-Approach Example



## RPQ Evaluation Tasks

| Name | Input | Task |
| :--- | :--- | :--- |
| RPQ-Boole | $\mathcal{D}, q$ | Decide whether $q(\mathcal{D})=\emptyset$. |
| RPQ-Eval | $\mathcal{D}, q$ | Compute the whole set $q(\mathcal{D})$. |
| RPQ-Count | $\mathcal{D}, q$ | Compute $\|q(\mathcal{D})\|$. |
| (Sorted) RPQ-Enum | $\mathcal{D}, q$ | Enumerate the whole set $q(\mathcal{D})$ |
|  |  | (lexicographically ordered). |

## RPQ Evaluation Tasks

| Name | Input | Task |
| :--- | :--- | :--- |
| RPQ-Boole | $\mathcal{D}, q$ | Decide whether $q(\mathcal{D})=\emptyset$. |
| RPQ-Eval | $\mathcal{D}, q$ | Compute the whole set $q(\mathcal{D})$. |
| RPQ-Count | $\mathcal{D}, q$ | Compute $\|q(\mathcal{D})\|$. |
| (Sorted) RPQ-Enum | $\mathcal{D}, q$ | Enumerate the whole set $q(\mathcal{D})$ |
|  |  | (lexicographically ordered). |

Updates: Adding/deleting isolated nodes, adding/deleting arcs.

## Research Question

- PG-approach good for simple tasks like checking $q(\mathcal{D})=\emptyset$ or $(u, v) \in q(\mathcal{D})$. What about computing, counting or enumerating $q(\mathcal{D})$ ?
- Is the PG-approach optimal?
- Can we complement upper bounds with conditional lower bounds?


## Fine-Grained Complexity and Conditional Lower Bounds

## Orthogonal Vectors

Orthogonal Vectors (OV)
Input: Sets $A, B$ each containing $n$ Boolean $d$-dimensional vectors.
Question: Are there orthogonal vectors $\vec{a} \in A$ and $\vec{b} \in B$ ?

## Orthogonal Vectors

Orthogonal Vectors (OV)
Input: Sets $A, B$ each containing $n$ Boolean $d$-dimensional vectors. Question: Are there orthogonal vectors $\vec{a} \in A$ and $\vec{b} \in B$ ?

OV-Hypothesis
For every $\epsilon>0$, OV cannot be solved in $\mathrm{O}\left(n^{2-\epsilon}\right.$ poly $\left.(d)\right)$.

## Boolean Matrix Multiplication

## Boolean Matrix Multiplication (BMM)

Input: Boolean $n \times n$ matrices $A, B$.
Task: Compute $A \times B$.

## Boolean Matrix Multiplication

## Boolean Matrix Multiplication (BMM)

Input: Boolean $n \times n$ matrices $A, B$.
Task: Compute $A \times B$.

## com-BMM-Hypothesis

For every $\epsilon>0$, BMM cannot be solved in $\mathrm{O}\left(n^{3-\epsilon}\right)$ by a combinatorial algorithm.

## Boolean Matrix Multiplication

Boolean Matrix Multiplication (BMM)
Input: Boolean $n \times n$ matrices $A, B$.
Task: Compute $A \times B$.

## com-BMM-Hypothesis

For every $\epsilon>0$, BMM cannot be solved in $\mathrm{O}\left(n^{3-\epsilon}\right)$ by a combinatorial algorithm.

## SBMM-Hypothesis

BMM cannot be solved in $\mathrm{O}(m)$, where $m=$ number of 1-entries.

## Our Results

## RPQ-Boole

Theorem
RPQ-Boole can be solved in time $\mathrm{O}(|\mathcal{D} \| q|)$.

## RPQ-Boole

## Theorem

RPQ-Boole can be solved in time $\mathrm{O}(|\mathcal{D} \| q|)$.

## Theorem

If RPQ-Boole can be solved in time

- $\mathrm{O}\left(|\mathcal{D}|^{2-\epsilon}+|q|^{2}\right)$, then OV-hypothesis fails.
- $\mathrm{O}\left(|\mathcal{D}|^{2}+|q|^{2-\epsilon}\right)$, then OV-hypothesis fails.
- $\mathrm{O}\left(\left|V_{\mathcal{D}}\right|^{3-\epsilon}+|q|^{3-\epsilon}\right)$, com-BMM-hypothesis fails.


## RPQ-Boole

## Theorem <br> RPQ-Boole can be solved in time $\mathrm{O}(|\mathcal{D} \| q|)$.

## Theorem

If RPQ-Boole can be solved in time

- $\mathrm{O}\left(|\mathcal{D}|^{2-\epsilon}+|q|^{2}\right)$, then OV-hypothesis fails.
- $\mathrm{O}\left(|\mathcal{D}|^{2}+|q|^{2-\epsilon}\right)$, then OV-hypothesis fails.
- $\mathrm{O}\left(\left|V_{\mathcal{D}}\right|^{3-\epsilon}+|q|^{3-\epsilon}\right)$, com-BMM-hypothesis fails.


## Data Complexity

From now on ALL bounds in data complexity!

## RPQ-Eval and RPQ-Count

Theorem RPQ-Eval (and RPQ-Count) can be solved in time $\mathrm{O}\left(\left|V_{\mathcal{D}} \| \mathcal{D}\right|\right)$.

## RPQ-Eval and RPQ-Count

Theorem RPQ-Eval (and RPQ-Count) can be solved in time $\mathrm{O}\left(\left|V_{\mathcal{D}} \| \mathcal{D}\right|\right)$.

## Theorem

If RPQ-Eval can be solved in time

- $\mathrm{O}\left(\left(\left|V_{\mathcal{D}}\right||\mathcal{D}|\right)^{1-\epsilon}\right)$, then com-BMM-hypothesis fails.
- $\mathrm{O}((|q(\mathcal{D})|+|\mathcal{D}|))$, then SBMM-hypothesis fails.


## RPQ-Eval and RPQ-Count

## Theorem

 RPQ-Eval (and RPQ-Count) can be solved in time $\mathrm{O}\left(\left|V_{\mathcal{D}} \| \mathcal{D}\right|\right)$.
## Theorem

If RPQ-Eval can be solved in time

- $\mathrm{O}\left(\left(\left|V_{\mathcal{D}}\right||\mathcal{D}|\right)^{1-\epsilon}\right)$, then com-BMM-hypothesis fails.
- $\mathrm{O}((|q(\mathcal{D})|+|\mathcal{D}|))$, then SBMM-hypothesis fails.


## Theorem

If $R P Q$-Count can be solved in time $O\left(\left(\left|V_{\mathcal{D}} \| \mathcal{D}\right|\right)^{1-\epsilon}\right)$ then the OV-hypothesis fails.

## RPQ-Enum - Upper Bound

## Theorem

Sorted RPQ-Enum can be solved with preprocessing $\mathrm{O}(|\mathcal{D}|)$, delay $\mathrm{O}(|\mathcal{D}|)$ and $\mathrm{O}(1)$ updates.

## RPQ-Enum - Upper Bound

## Theorem

Sorted RPQ-Enum can be solved with preprocessing $\mathrm{O}(|\mathcal{D}|)$, delay $\mathrm{O}(|\mathcal{D}|)$ and $\mathrm{O}(1)$ updates.

## Some Thoughts

- Linear preprocessing is reasonable.
- Linear delay is bad.
- What about updates??


## RPQ-Enum - Lower Bounds

Conditional Lower Bounds
Linear preprocessing and

- constant delay? No!


## RPQ-Enum - Lower Bounds

Conditional Lower Bounds
Linear preprocessing and

- constant delay? No!
- delay sublinear in $\left|V_{\mathcal{D}}\right|$ ? No!


## RPQ-Enum - Lower Bounds

## Conditional Lower Bounds

Linear preprocessing and

- constant delay? No!
- delay sublinear in $\left|V_{\mathcal{D}}\right|$ ? No!
- delay sublinear in $|\mathcal{D}|$ ? Not if we also want updates!


## RPQ-Enum - Lower Bounds

## Conditional Lower Bounds

Linear preprocessing and

- constant delay? No!
- delay sublinear in $\left|V_{\mathcal{D}}\right|$ ? No!
- delay sublinear in $|\mathcal{D}|$ ? Not if we also want updates!


## Open Question

RPQ-Enum with $\mathrm{O}(|\mathcal{D}|)$ preprocessing and $\mathrm{O}\left(\left|V_{\mathcal{D}}\right|\right)$ delay???

## RPQ-Enum - Lower Bounds

## Conditional Lower Bounds

Linear preprocessing and

- constant delay? No!
- delay sublinear in $\left|V_{\mathcal{D}}\right|$ ? No!
- delay sublinear in $|\mathcal{D}|$ ? Not if we also want updates!

Open Question
RPQ-Enum with $\mathrm{O}(|\mathcal{D}|)$ preprocessing and $\mathrm{O}\left(\left|V_{\mathcal{D}}\right|\right)$ delay???

Next objective:
Just any enumeration that guarantees delay sublinear in $|\mathcal{D}|$.

## Three Approaches to Sublinear Delay

First Approach: Representative Subset of Solution Set
A "representative" subset $A \subseteq q(\mathcal{D})$ can be enumerated with linear preprocessing and constant delay.

## Three Approaches to Sublinear Delay

First Approach: Representative Subset of Solution Set
A "representative" subset $A \subseteq q(\mathcal{D})$ can be enumerated with linear preprocessing and constant delay.
$\bar{\Delta}(\mathcal{D})$ denotes the average degree of $\mathcal{D}$.
Second Approach: Super-Linear Preprocessing
Sorted RPQ-Enum can be solved with preprocessing $\mathrm{O}(\log (\bar{\Delta}(\mathcal{D})) \bar{\Delta}(\mathcal{D})|\mathcal{D}|)$ and delay $\mathrm{O}\left(\left|V_{\mathcal{D}}\right|\right)$.

## Three Approaches to Sublinear Delay

First Approach: Representative Subset of Solution Set
A "representative" subset $A \subseteq q(\mathcal{D})$ can be enumerated with linear preprocessing and constant delay.
$\bar{\Delta}(\mathcal{D})$ denotes the average degree of $\mathcal{D}$.
Second Approach: Super-Linear Preprocessing
Sorted RPQ-Enum can be solved with preprocessing $\mathrm{O}(\log (\bar{\Delta}(\mathcal{D})) \bar{\Delta}(\mathcal{D})|\mathcal{D}|)$ and delay $\mathrm{O}\left(\left|V_{\mathcal{D}}\right|\right)$.
$\Delta(\mathcal{D})$ denotes the maximum degree of $\mathcal{D}$.

## Third Approach: Restricted Class of RPQs

For a $Q \subseteq R P Q, R P Q-E n u m$ can be solved with preprocessing $\mathrm{O}(|\mathcal{D}|)$ and delay $\mathrm{O}(\Delta(\mathcal{D}))$.

## Third Approach: Restricted Class of RPQs

- Short RPQ (S-RPQ):

$$
q=\left(x_{1} \vee \ldots \vee x_{k}\right) \text { or } q=\left(x_{1} \vee \ldots \vee x_{k}\right)\left(y_{1} \vee \ldots \vee y_{k^{\prime}}\right)
$$

$$
\text { where } x_{1}, \ldots, x_{k}, y_{1}, \ldots, y_{k^{\prime}} \in \Sigma \text {. }
$$

Example: $q=(a \vee b)(a \vee c \vee d)$.

## Third Approach: Restricted Class of RPQs

- Short RPQ (S-RPQ):
$q=\left(x_{1} \vee \ldots \vee x_{k}\right)$ or $q=\left(x_{1} \vee \ldots \vee x_{k}\right)\left(y_{1} \vee \ldots \vee y_{k^{\prime}}\right)$, where $x_{1}, \ldots, x_{k}, y_{1}, \ldots, y_{k^{\prime}} \in \Sigma$.

Example: $q=(a \vee b)(a \vee c \vee d)$.

- Basic Transitive RPQ (BT-RPQ):
$q=\left(x_{1} \vee \ldots \vee x_{k}\right)^{*}$ or $q=\left(x_{1} \vee \ldots \vee x_{k}\right)^{+}$, where $x_{1}, \ldots, x_{k} \in \Sigma$.
Example: $q=(a \vee c \vee d)^{+}$.


## Third Approach: Restricted Class of RPQs

- Short RPQ (S-RPQ):

$$
q=\left(x_{1} \vee \ldots \vee x_{k}\right) \text { or } q=\left(x_{1} \vee \ldots \vee x_{k}\right)\left(y_{1} \vee \ldots \vee y_{k^{\prime}}\right)
$$

where $x_{1}, \ldots, x_{k}, y_{1}, \ldots, y_{k^{\prime}} \in \Sigma$.
Example: $q=(\mathrm{a} \vee \mathrm{b})(\mathrm{a} \vee \mathrm{c} \vee \mathrm{d})$.

- Basic Transitive RPQ (BT-RPQ):
$q=\left(x_{1} \vee \ldots \vee x_{k}\right)^{*}$ or $q=\left(x_{1} \vee \ldots \vee x_{k}\right)^{+}$, where $x_{1}, \ldots, x_{k} \in \Sigma$.
Example: $q=(a \vee c \vee d)^{+}$.
- Alternation Closure:
$V(S-R P Q \cup B T-R P Q)=$
$\left\{\left(q_{1} \vee \ldots \vee q_{m}\right) \mid q_{i} \in \mathrm{~S}-\mathrm{RPQ} \cup \mathrm{BT}-\mathrm{RPQ}, 1 \leq i \leq m\right\}$.
Example: $q=\left(a b \vee c^{*} \vee b(c \vee d) \vee(a \vee b \vee d)^{+}\right)$


## Third Approach: Restricted Class of RPQs

Theorem
Semi-sorted Enum $(V(S-R P Q \cup B T-R P Q))$ can be solved with preprocessing $\mathrm{O}(|\mathcal{D}|)$ and delay $\mathrm{O}(\Delta(\mathcal{D}))$.

## Third Approach: Restricted Class of RPQs

## Theorem

Semi-sorted Enum $(V(S-R P Q \cup B T-R P Q))$ can be solved with preprocessing $\mathrm{O}(|\mathcal{D}|)$ and delay $\mathrm{O}(\Delta(\mathcal{D}))$.

## Proof Sketch

- Semi-sorted Enum(S-RPQ) and Enum(BT-RPQ) can be solved with preprocessing $\mathrm{O}(|\mathcal{D}|)$ and delay $\mathrm{O}(\Delta(\mathcal{D}))$.


## Third Approach: Restricted Class of RPQs

## Theorem

Semi-sorted Enum $(V(S-R P Q \cup B T-R P Q))$ can be solved with preprocessing $\mathrm{O}(|\mathcal{D}|)$ and delay $\mathrm{O}(\Delta(\mathcal{D}))$.

## Proof Sketch

- Semi-sorted Enum(S-RPQ) and Enum(BT-RPQ) can be solved with preprocessing $\mathrm{O}(|\mathcal{D}|)$ and delay $\mathrm{O}(\Delta(\mathcal{D}))$.
- For every $Q \subseteq \mathrm{RPQ}$ : Semi-sorted Enum $(Q)$ can be solved with linear preprocessing and some delay, then Enum $(\bigvee(Q))$ can be solved with the same preprocessing and delay.


## Third Approach: Restricted Class of RPQs

## Theorem

Semi-sorted Enum $(V(S-R P Q \cup B T-R P Q))$ can be solved with preprocessing $\mathrm{O}(|\mathcal{D}|)$ and delay $\mathrm{O}(\Delta(\mathcal{D}))$.

## Proof Sketch

- Semi-sorted Enum(S-RPQ) and Enum(BT-RPQ) can be solved with preprocessing $\mathrm{O}(|\mathcal{D}|)$ and delay $\mathrm{O}(\Delta(\mathcal{D}))$.
- For every $Q \subseteq \mathrm{RPQ}$ : Semi-sorted Enum $(Q)$ can be solved with linear preprocessing and some delay, then Enum $(\bigvee(Q))$ can be solved with the same preprocessing and delay.


## Theorem

If RPQ-Enum (S-RPQ) can be solved with preprocessing $\mathrm{O}\left(\left|V_{\mathcal{D}}\right|^{3-\epsilon}\right)$ and delay $\mathrm{O}\left(|\Delta(\mathcal{D})|^{1-\epsilon}\right)$, then the com-BMM-hypothesis fails.

Thank you very much for your attention.

